



# Multiple Views of a Virtual World Integrated With Real Images

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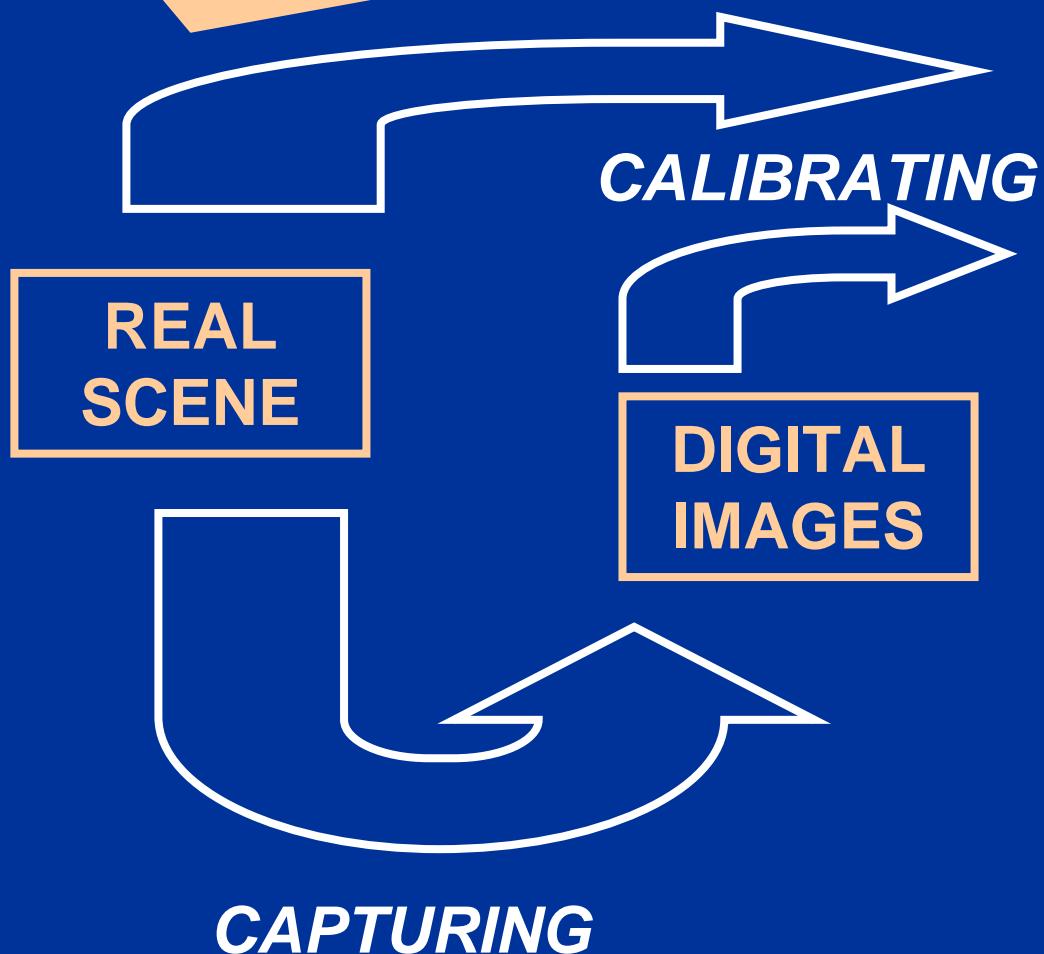
# GOALS

- A standard system for generating a 3D scene with real images
- Coherent integration between synthetic objects and real images
- Multiple views and animations effects

# INTEGRATION ASPECTS

- CONSISTENCY OF GEOMETRY
- CONSISTENCY OF ILLUMINATION
- CONSISTENCY OF TIME

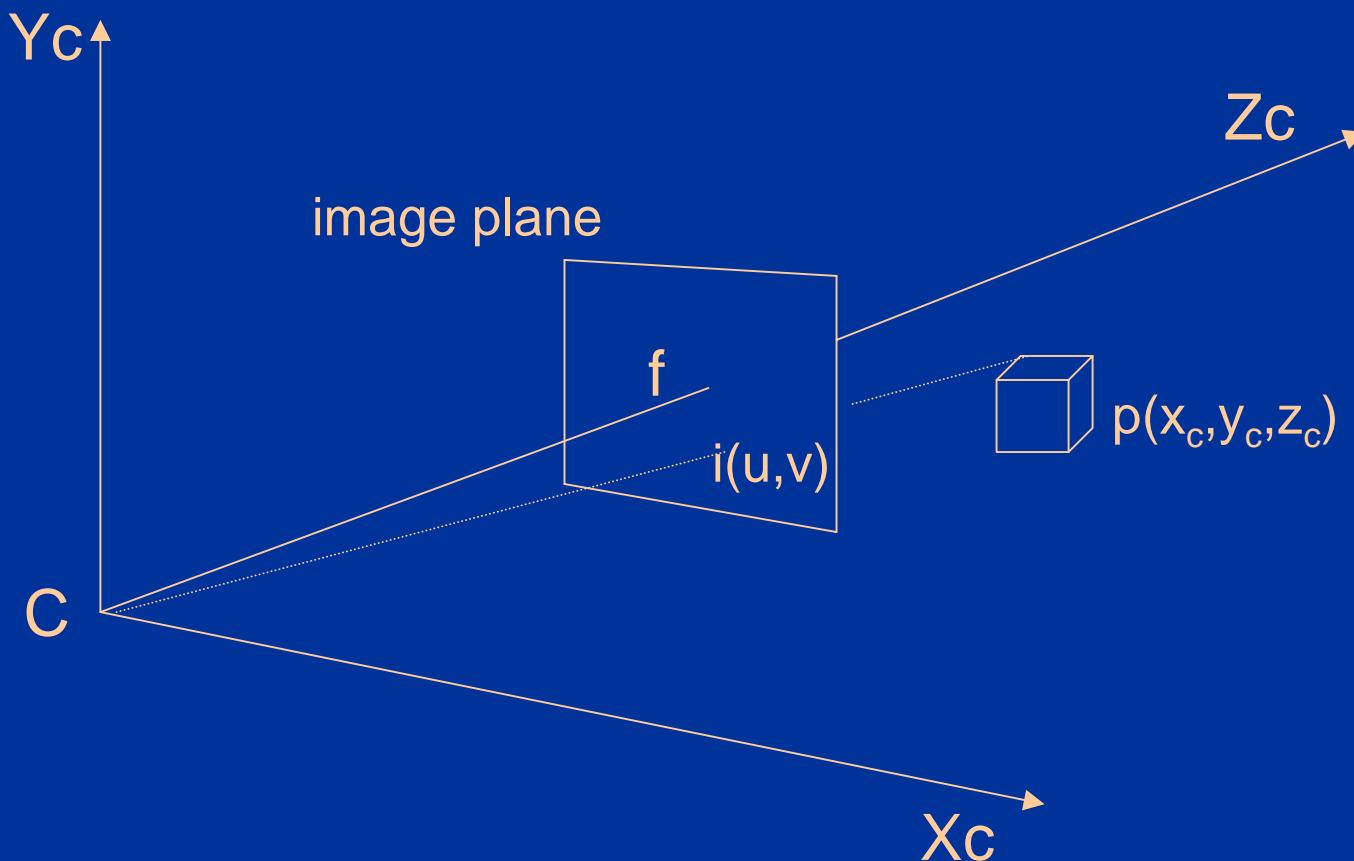
# INTEGRATION SYSTEM



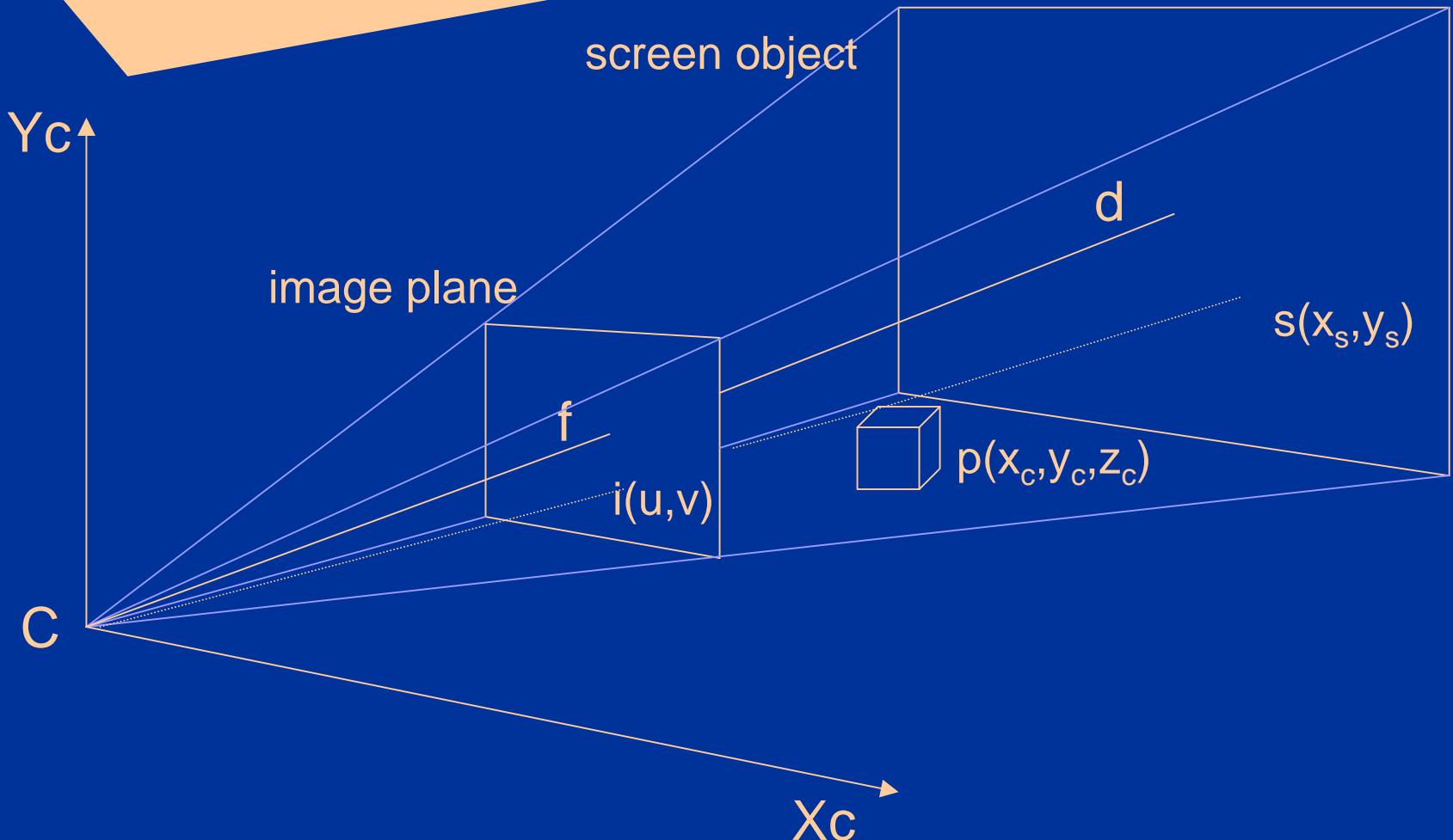
# INTEGRATION SYSTEM

- Capturing a SEQUENCE OF IMAGES
- CALIBRATING camera parameters
- Creating 3D SYNTHETIC OBJECTS
- Adding a 3D SCREEN OBJECT
- Adding a VIRTUAL CAMERA

# CAMERA MODEL



# CAMERA MODEL



# CALIBRATION

- Deduce the real camera position and orientation
- We need to know real points and its corresponding points in the image to know internal and external parameters

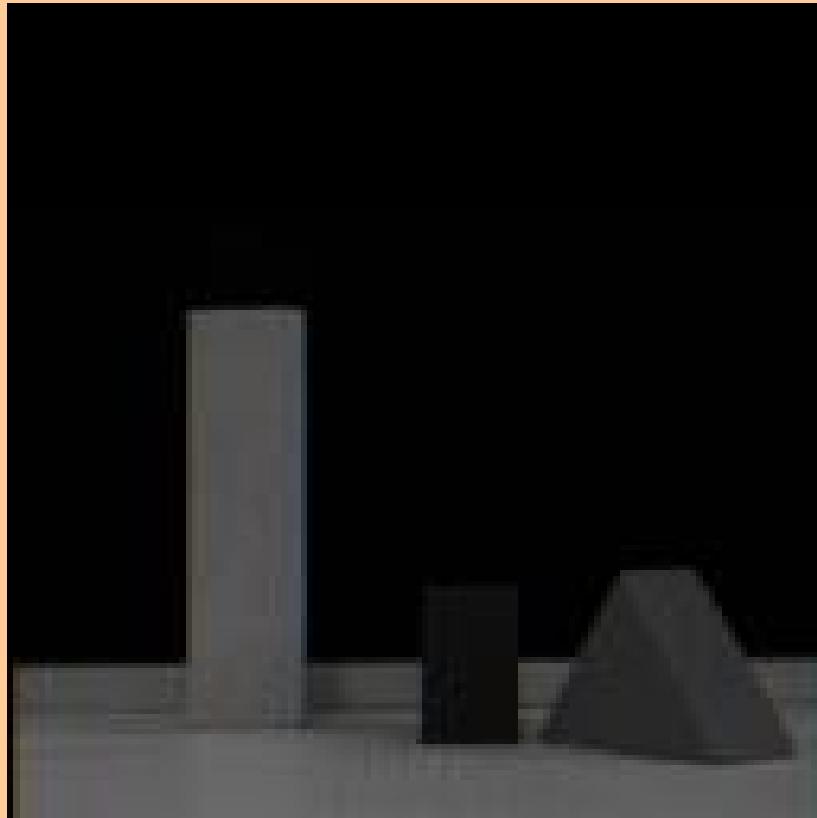
# CALIBRATION

- We assume *pinhole* model (ideal camera)
- We have matching points  $p(x,y,z)$  and  $i(u,v)$  with

$$p(x_c, y_c, z_c) = R(T(p(x, y, z))) \text{ and}$$
$$i(u, v) = P(p(x_c, y_c, z_c))$$

we can deduce the translation and rotation

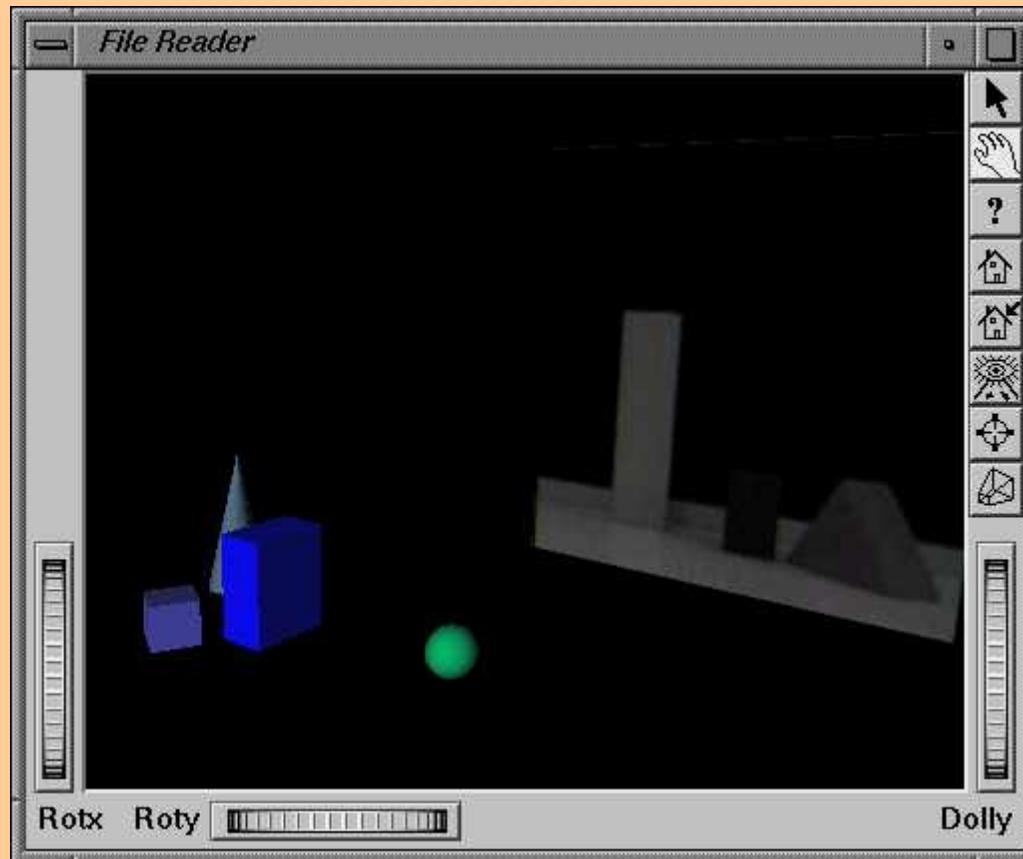
# Integration



# Captured Image

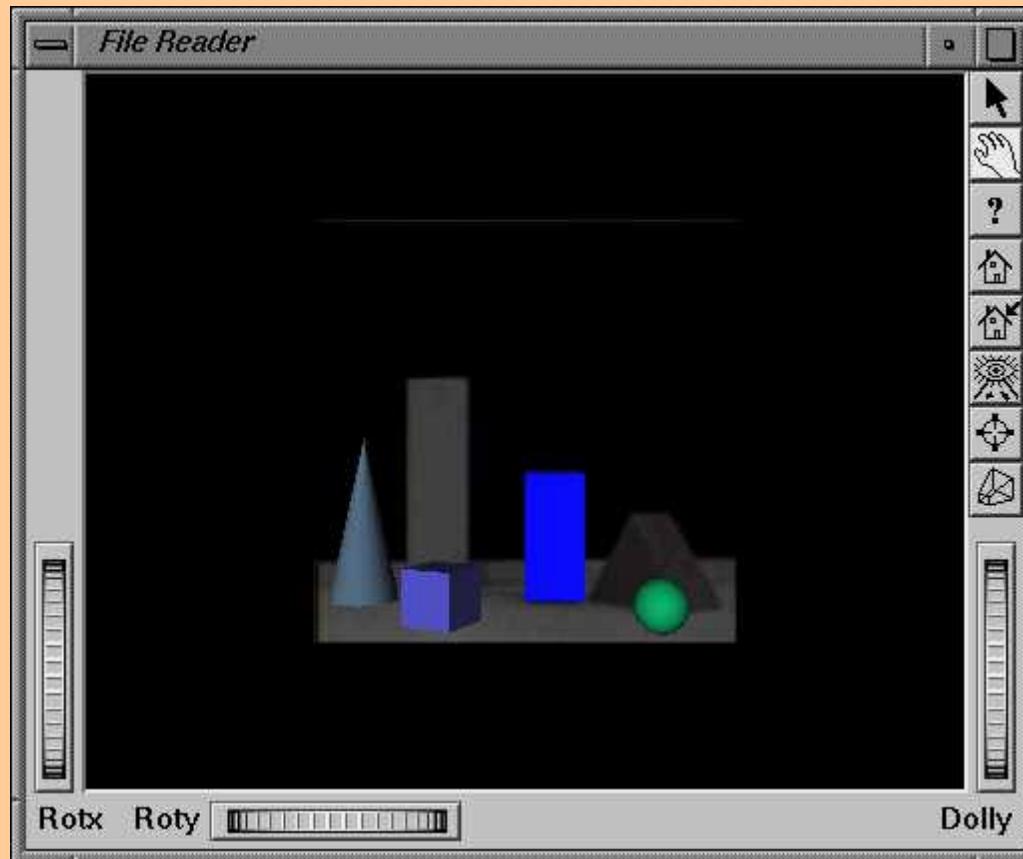
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Moscow, Russia, <http://www.graphicon.ru/>

# Integration



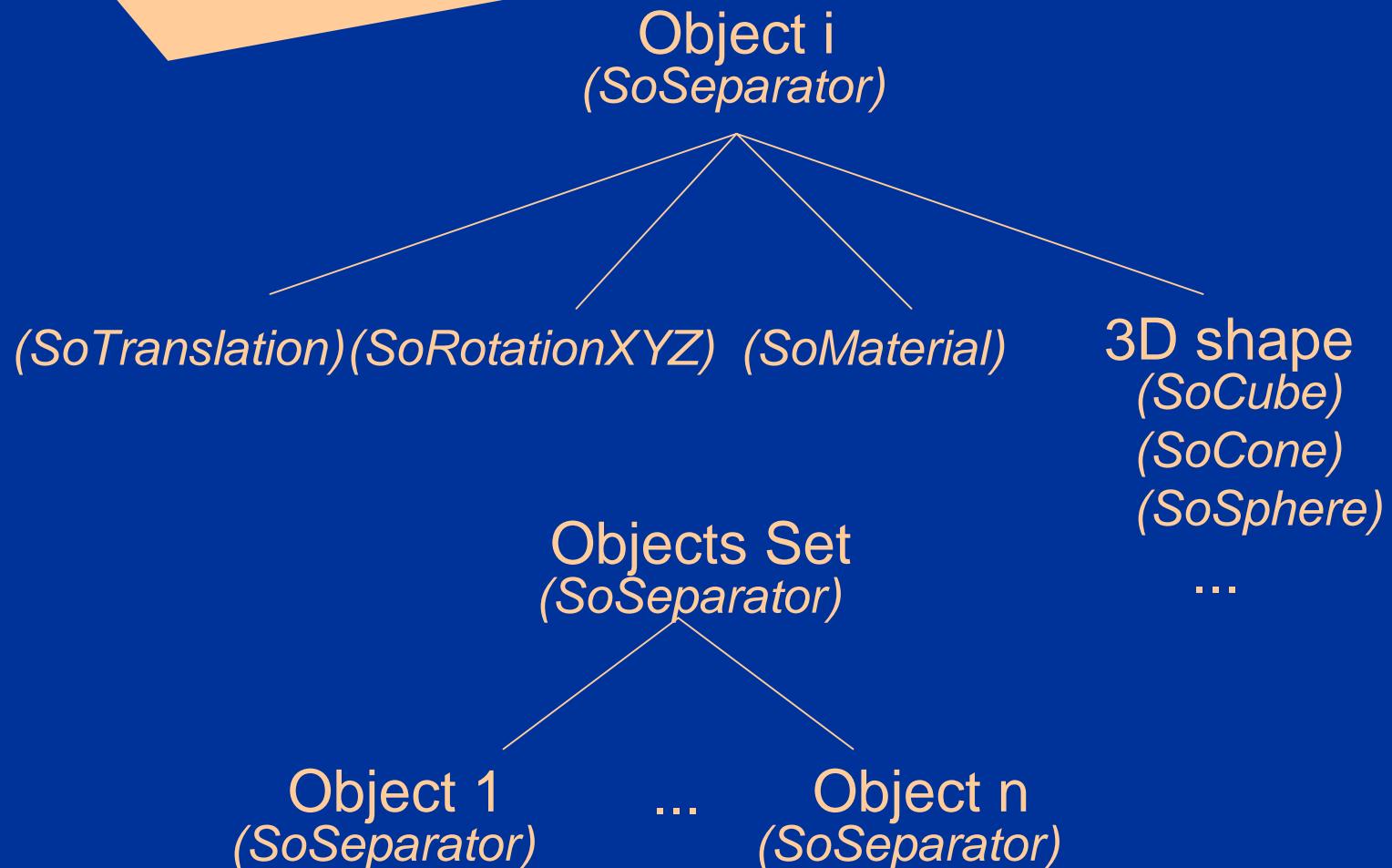
## 3D Scene + Screen Object

# Integration

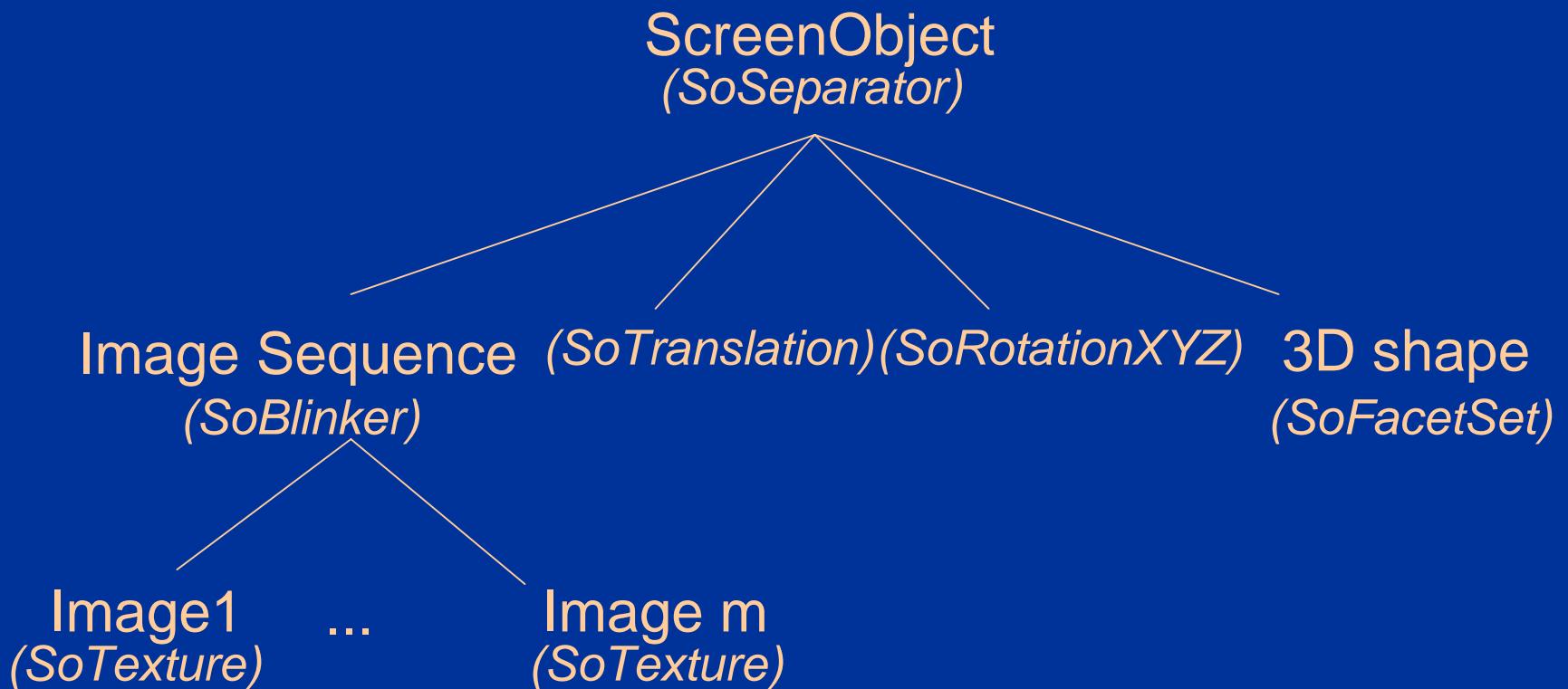


## View of the Integrated Scene

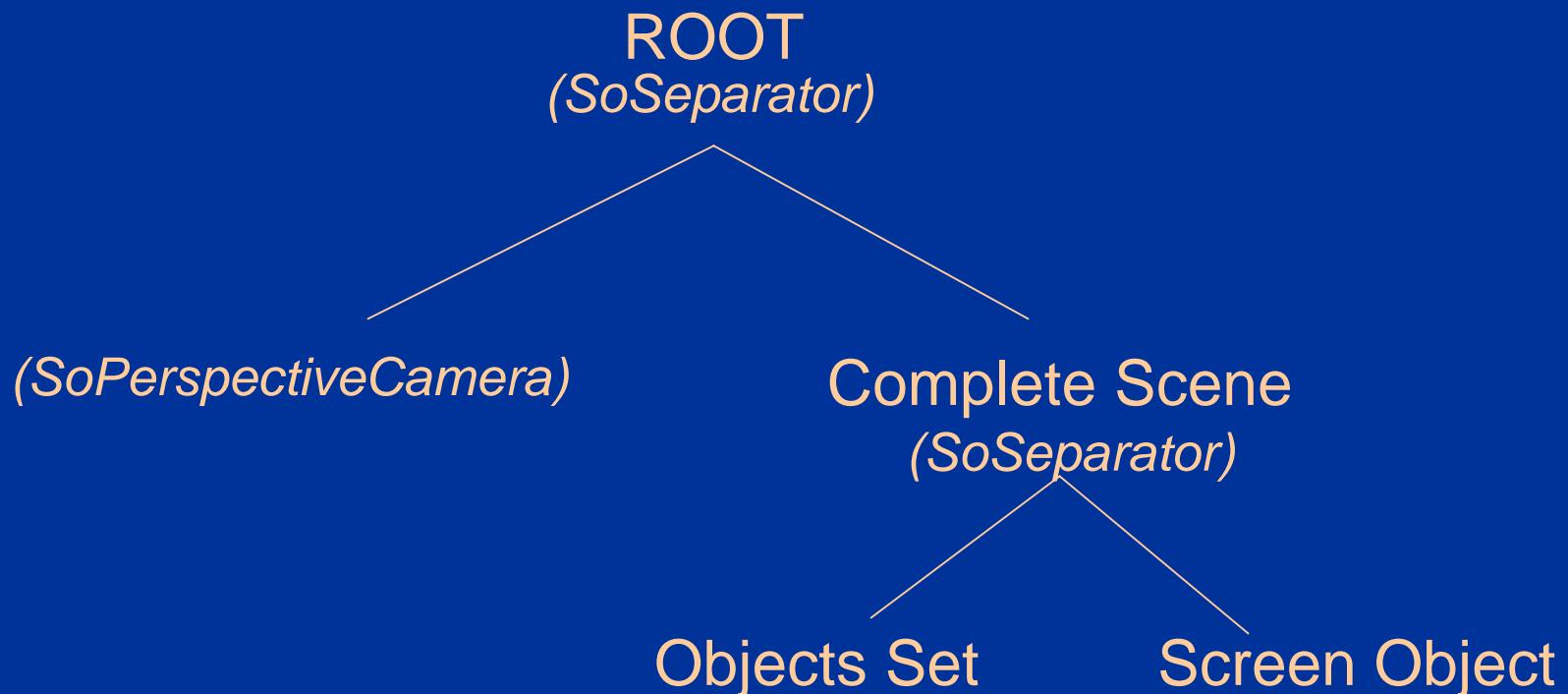
# SYNTHETIC OBJECTS



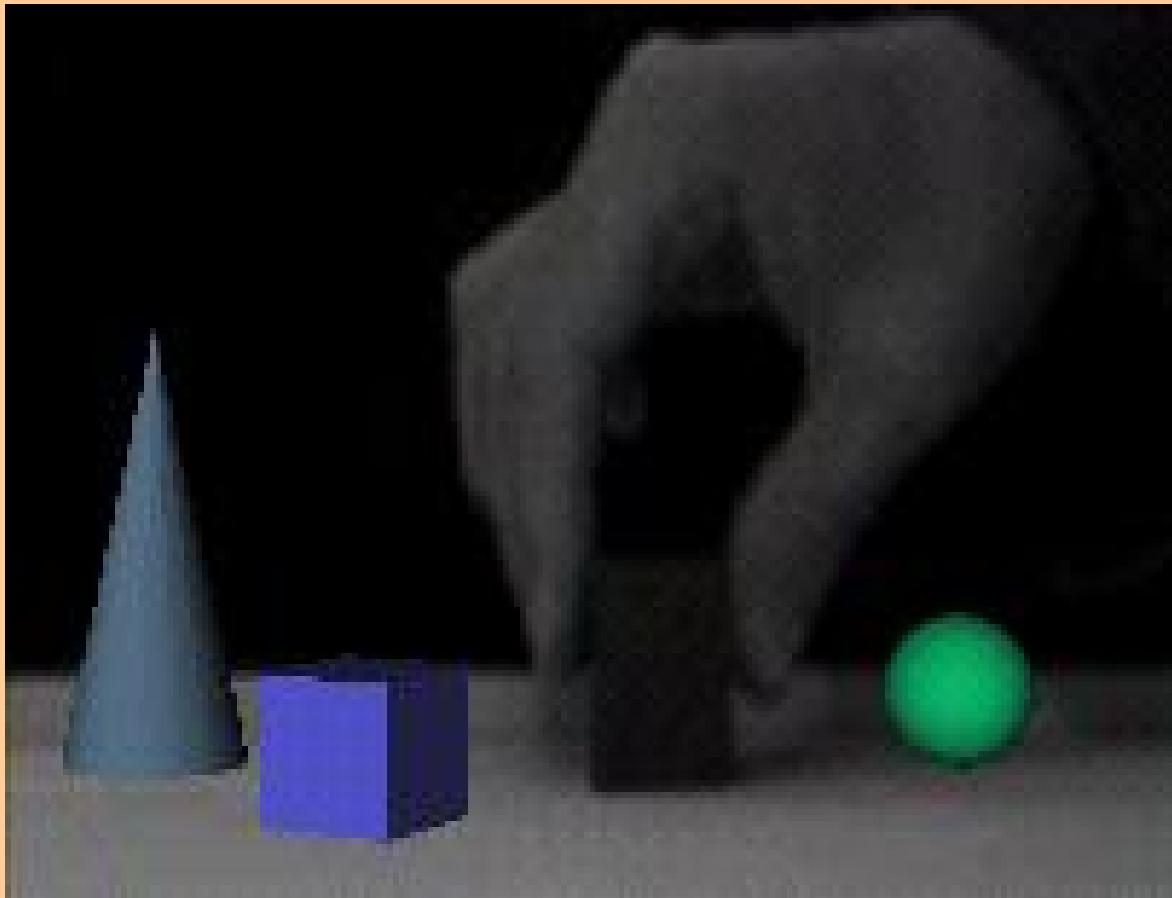
# SCREEN OBJECT



# INTEGRATED 3D SCENE

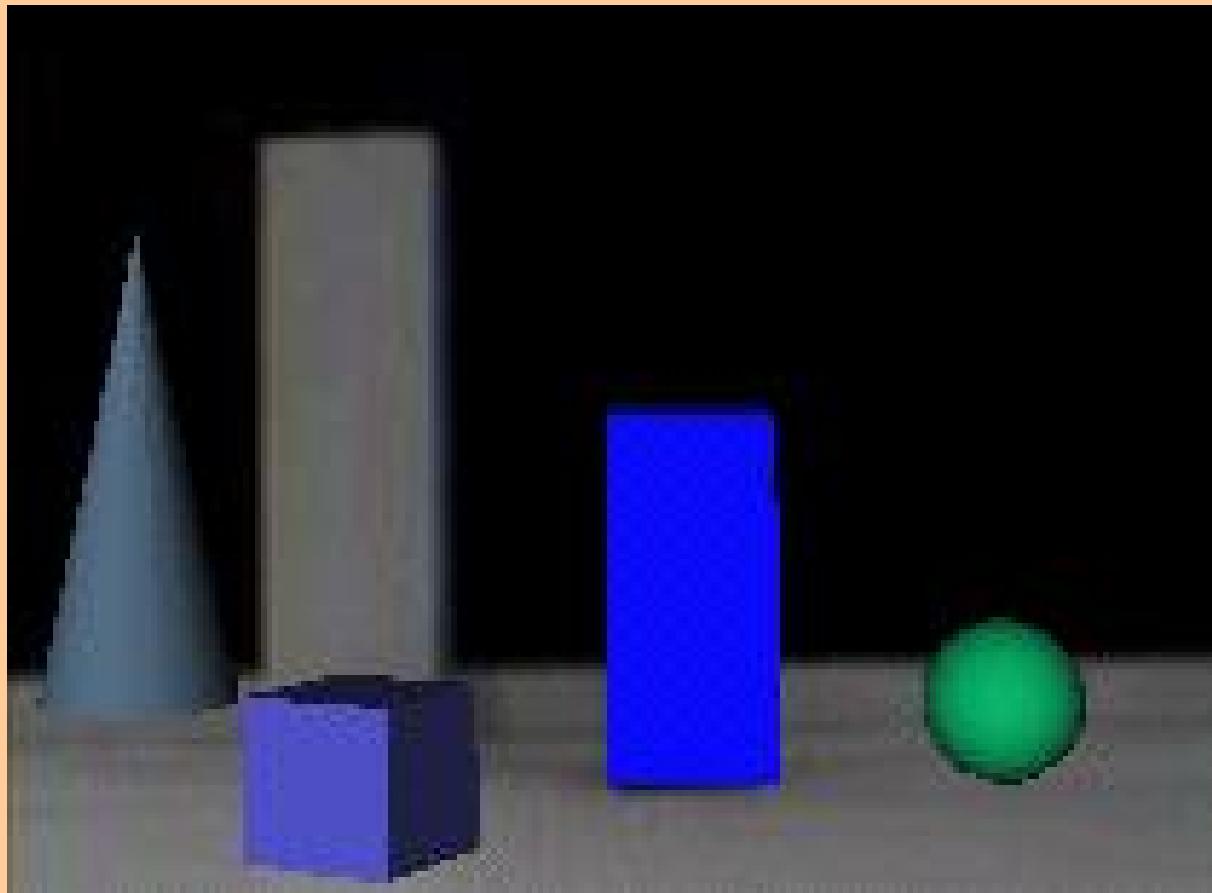


# Video Integration



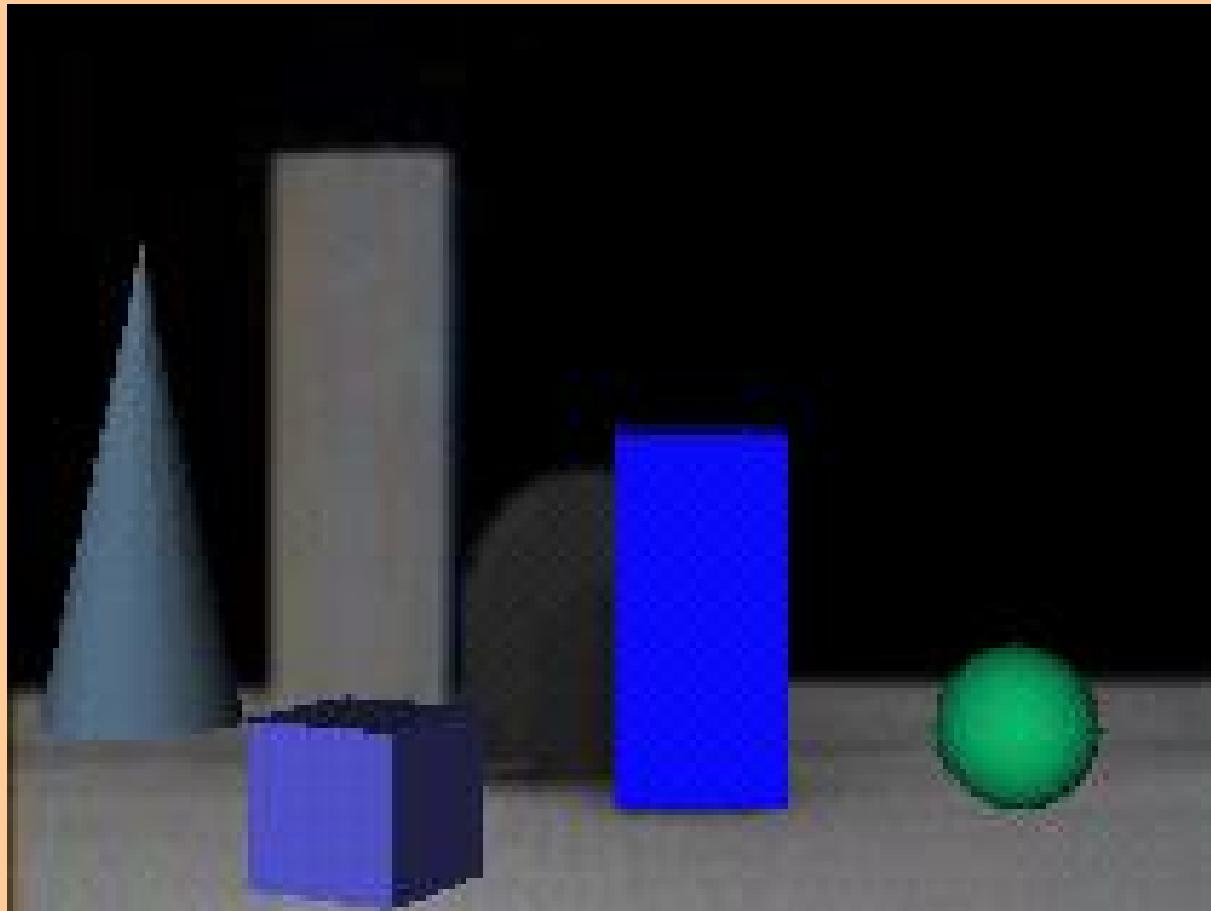
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Moscow, Russia, <http://www.graphicon.ru/>

# Video Integration



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# Video Integration



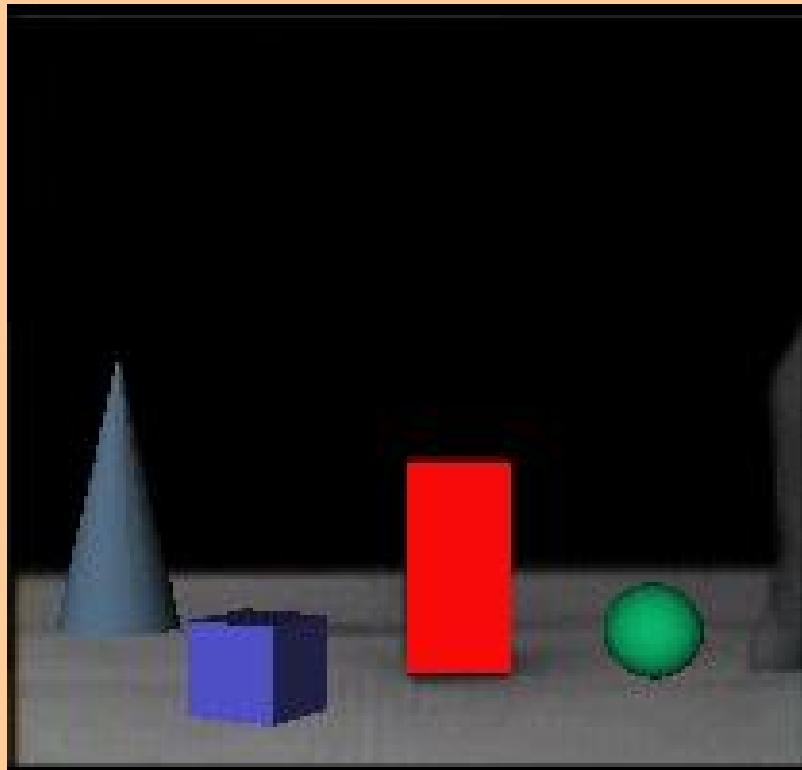
# Interactions



## Image sequence

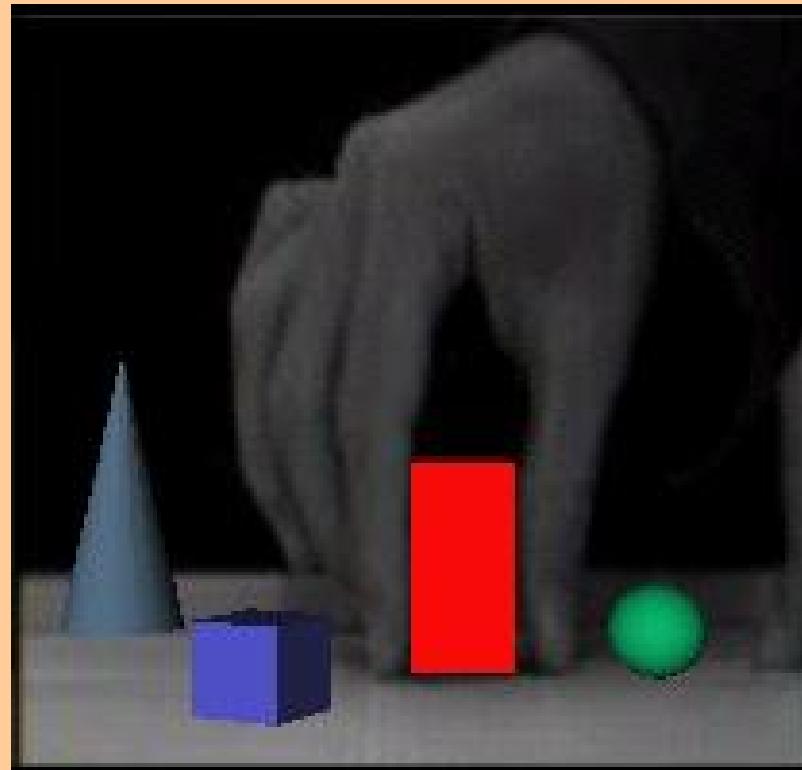
International Conference Graphicon 1999,  
Moscow, Russia, <http://www.graphicon.ru/>

# Interactions



## 3D Synthetic Scene

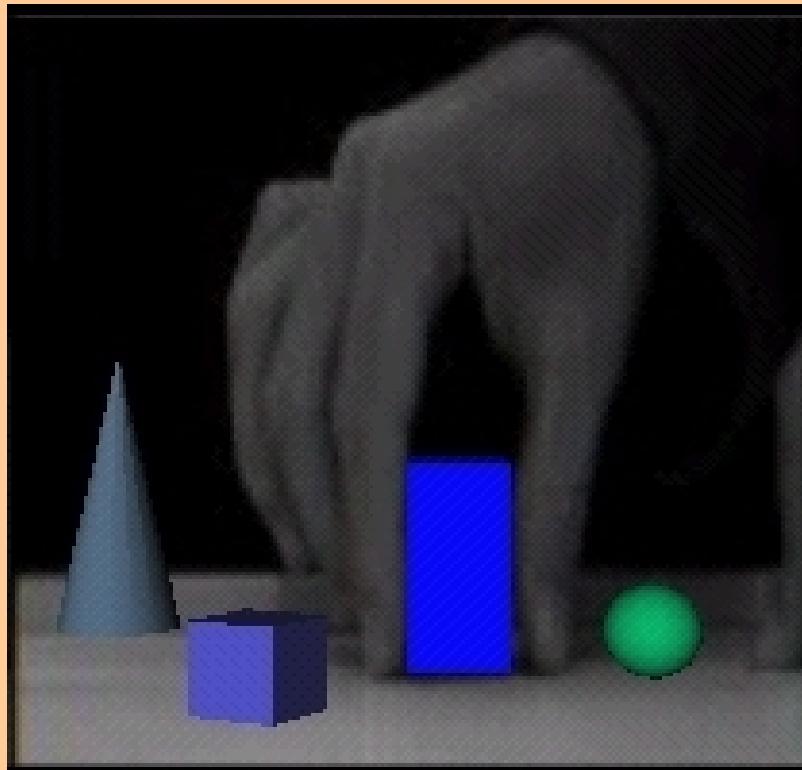
# Interactions



# Integration

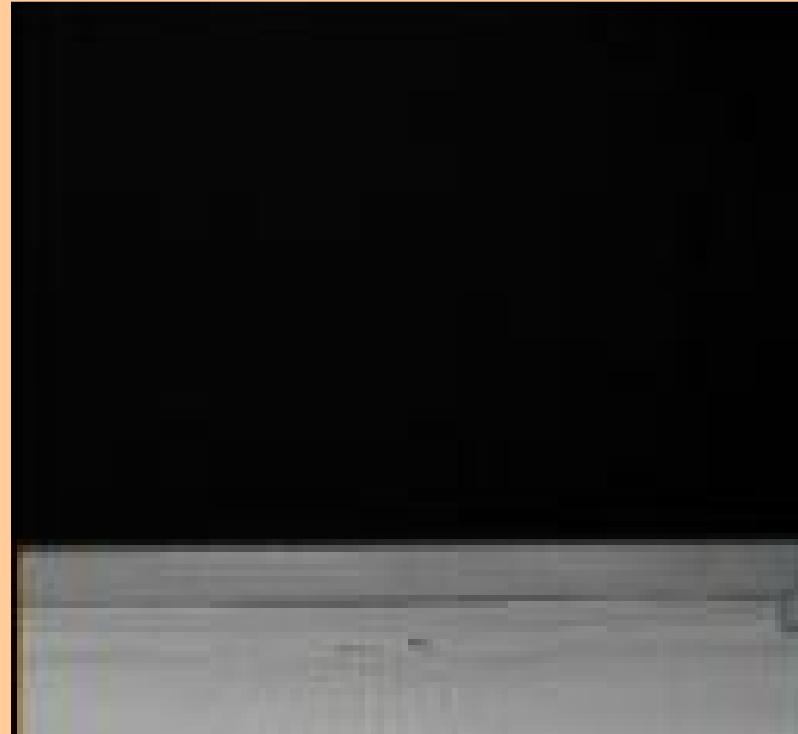
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# Interactions



## Object's response

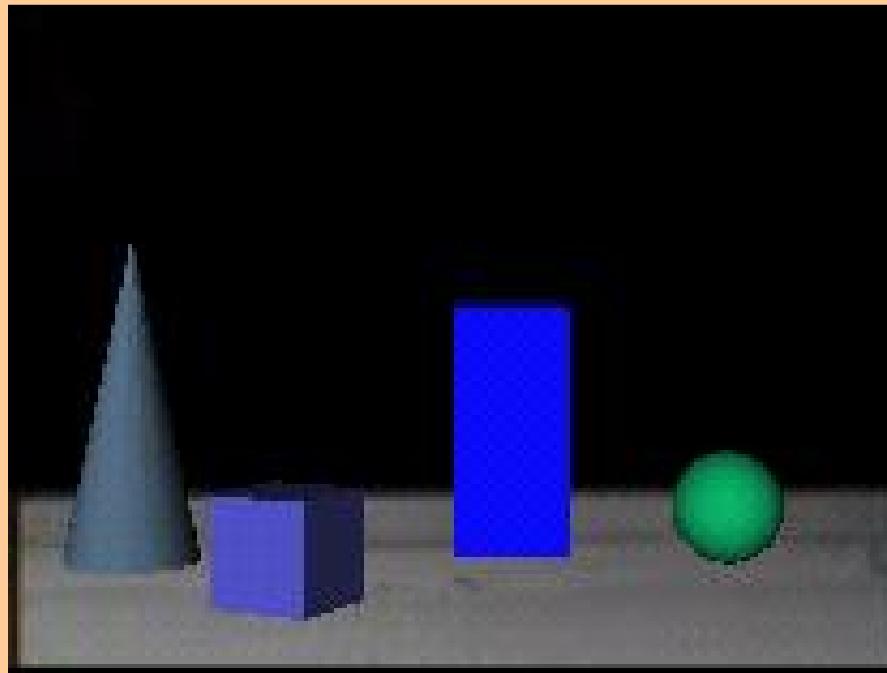
# Changing reference



## Image sequence

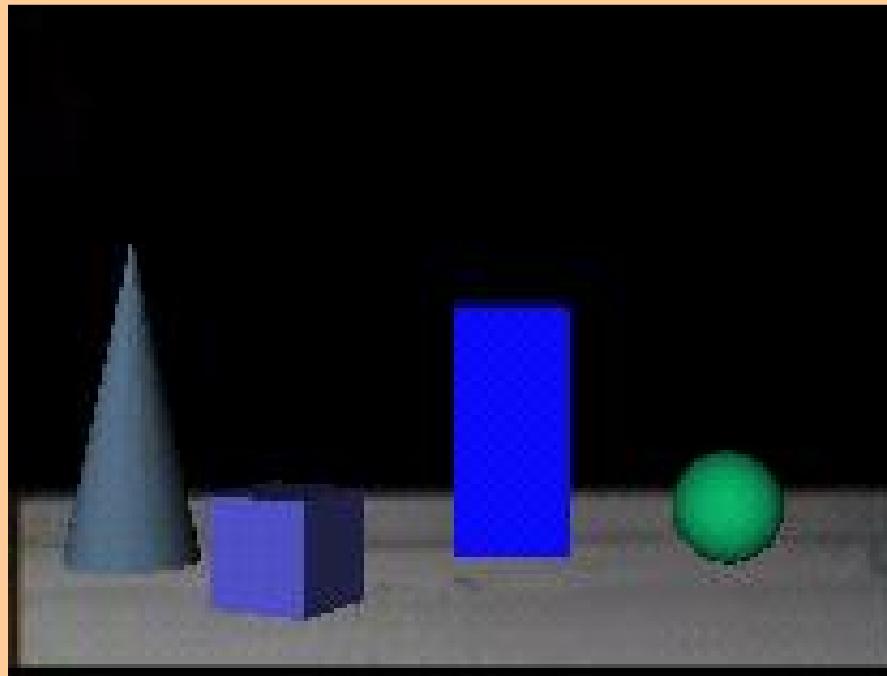
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# Changing reference



## 3D Synthetic Scene

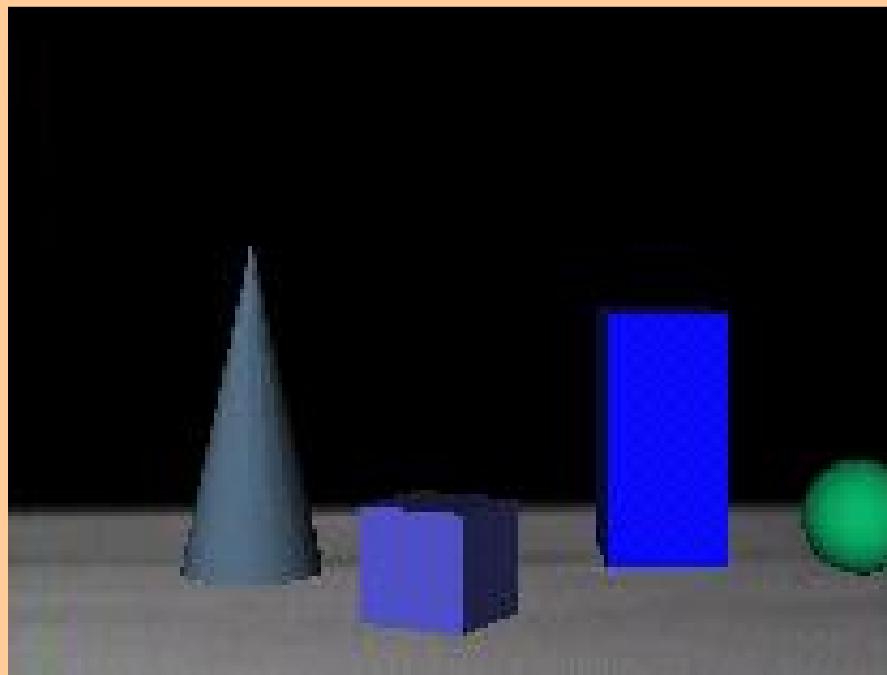
# Changing reference



## Original reference point

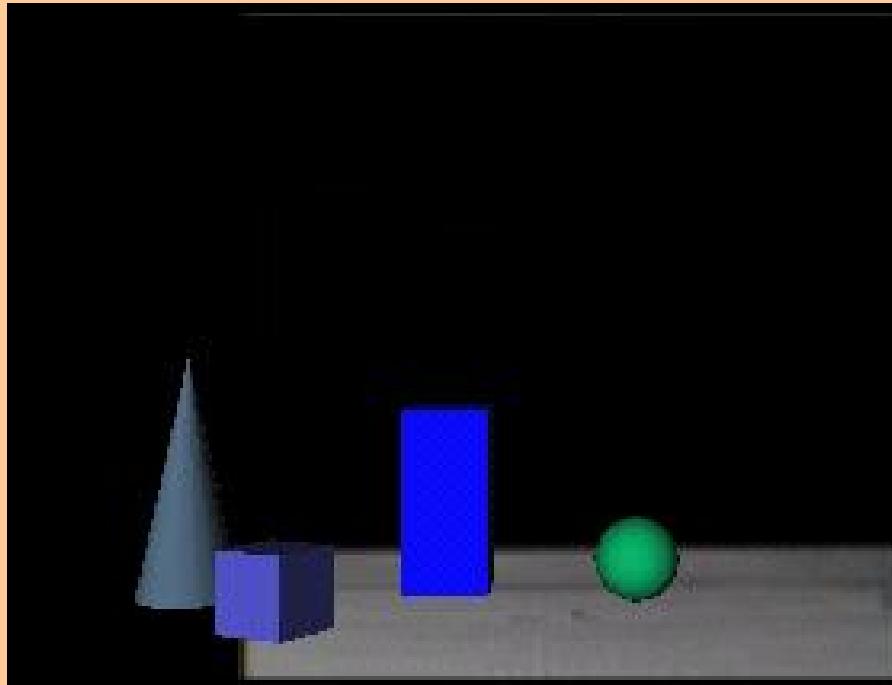
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# Changing reference



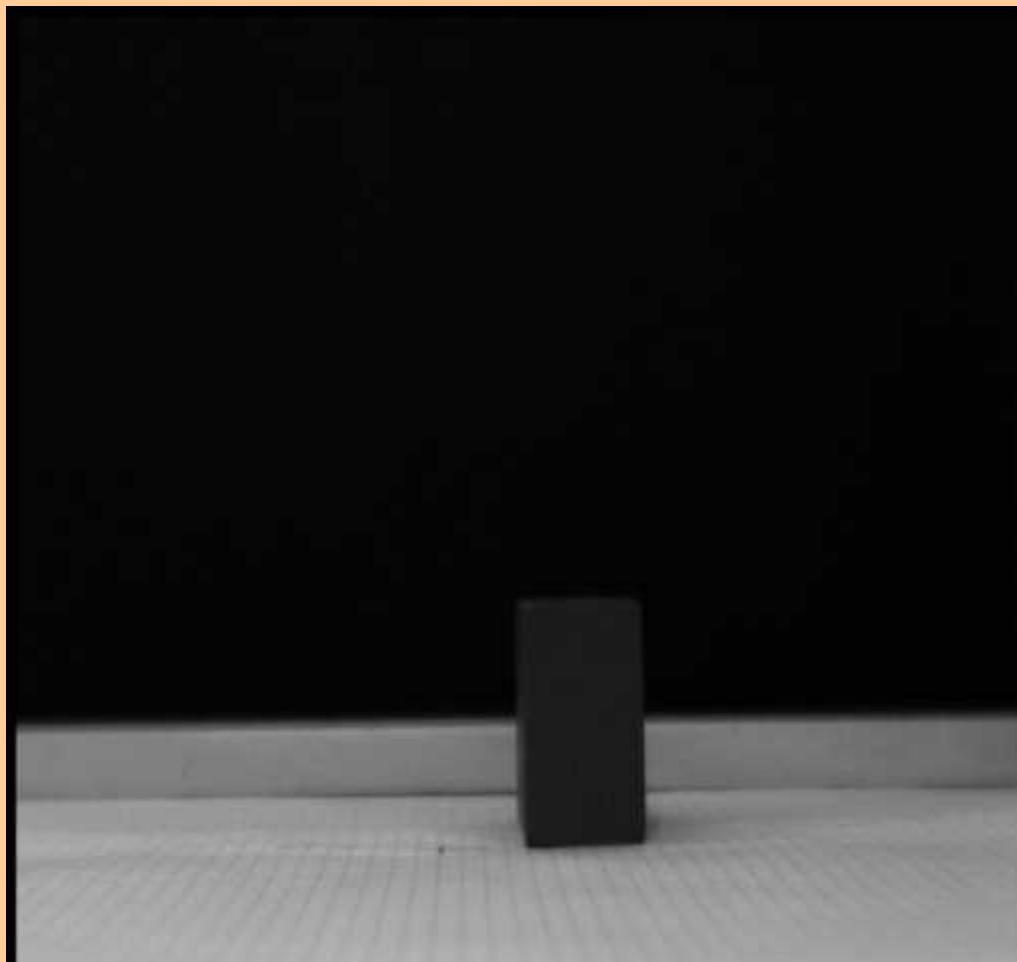
## Other reference point

# Animations



## Synthetic object animation

# Multiple Views



## Camera 1

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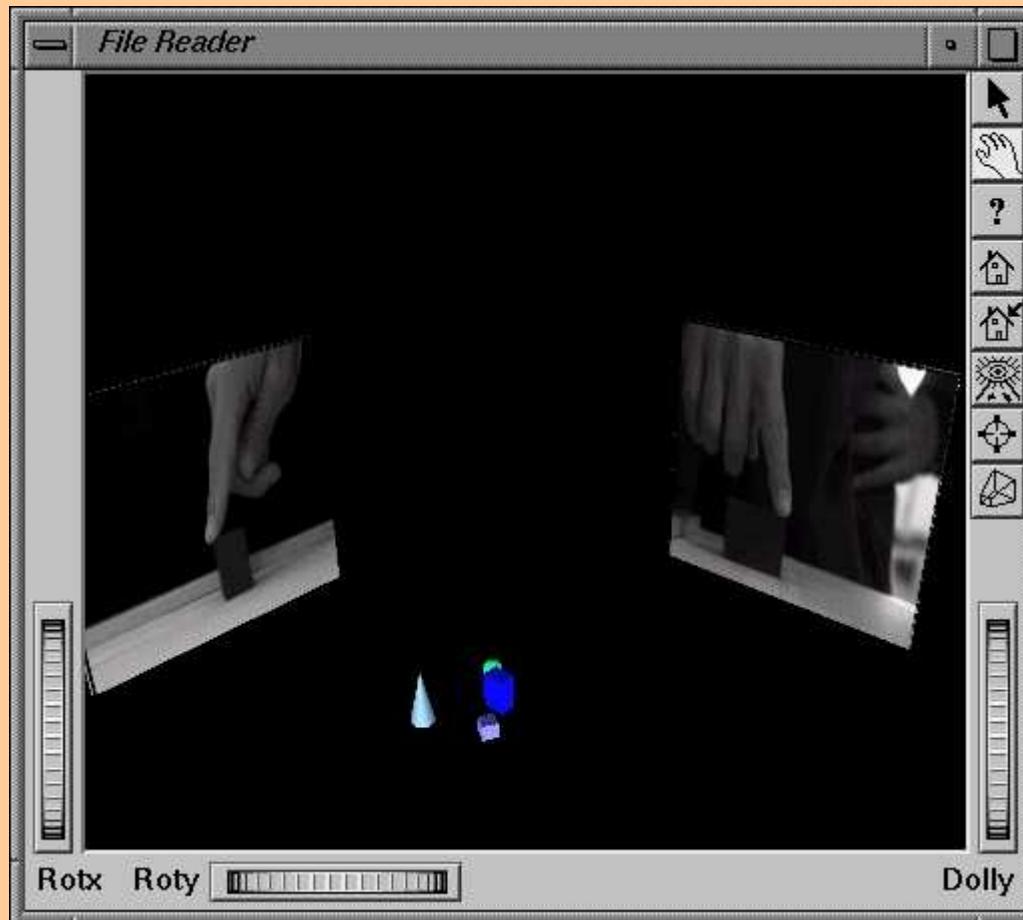
# Multiple Views



## Camera 2

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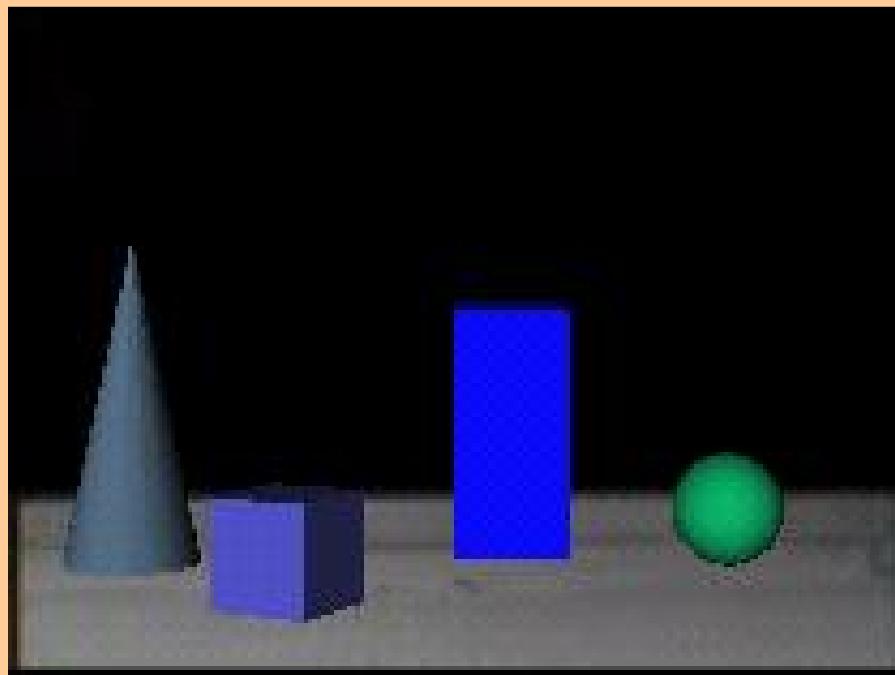
# Multiple Views



## 3D Scene + Screen Object

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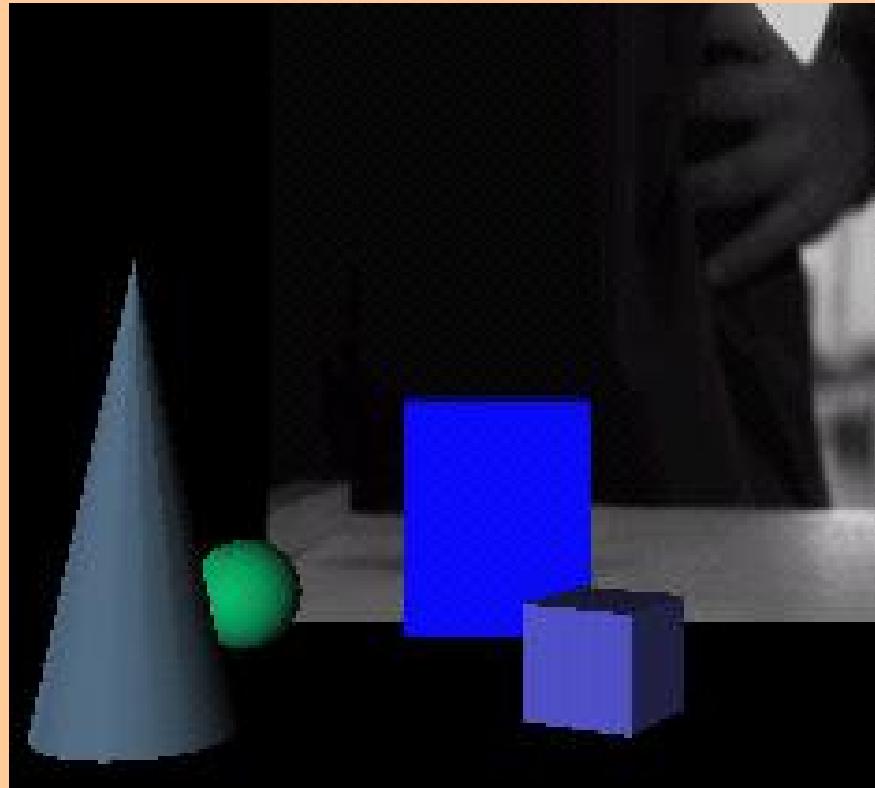
# Multiple Views



## View 1 of the integration

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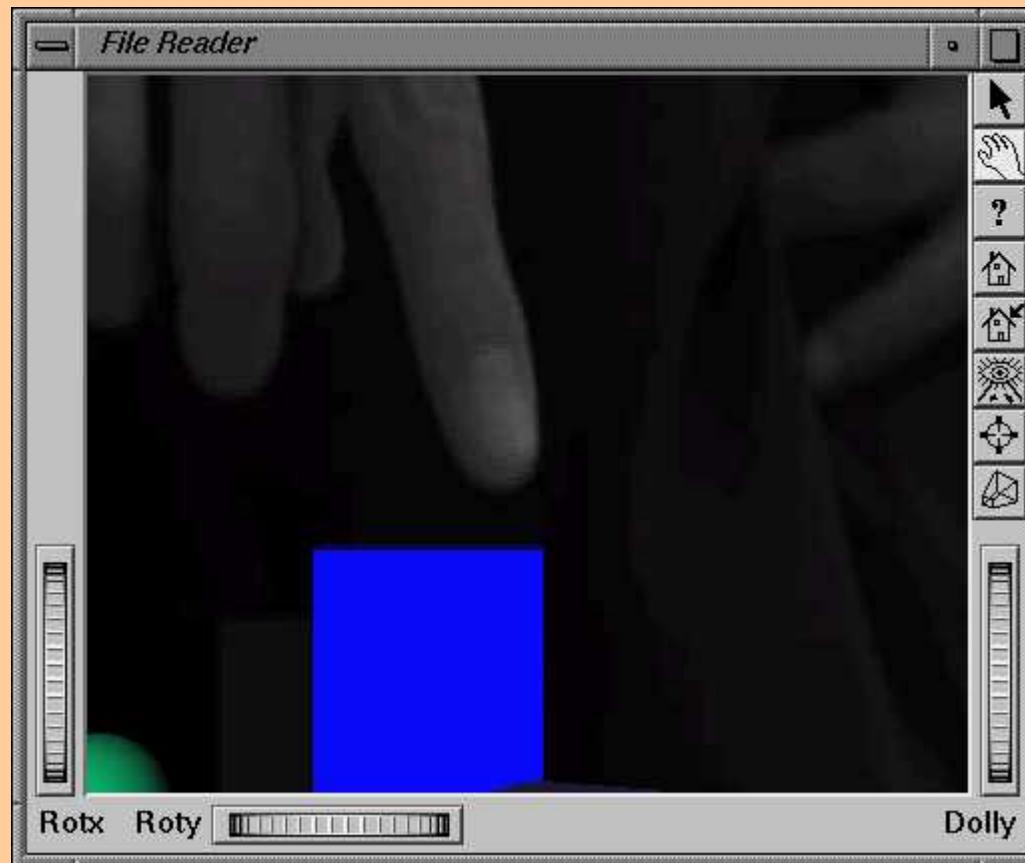
# Multiple Views



## View 2 of the integration

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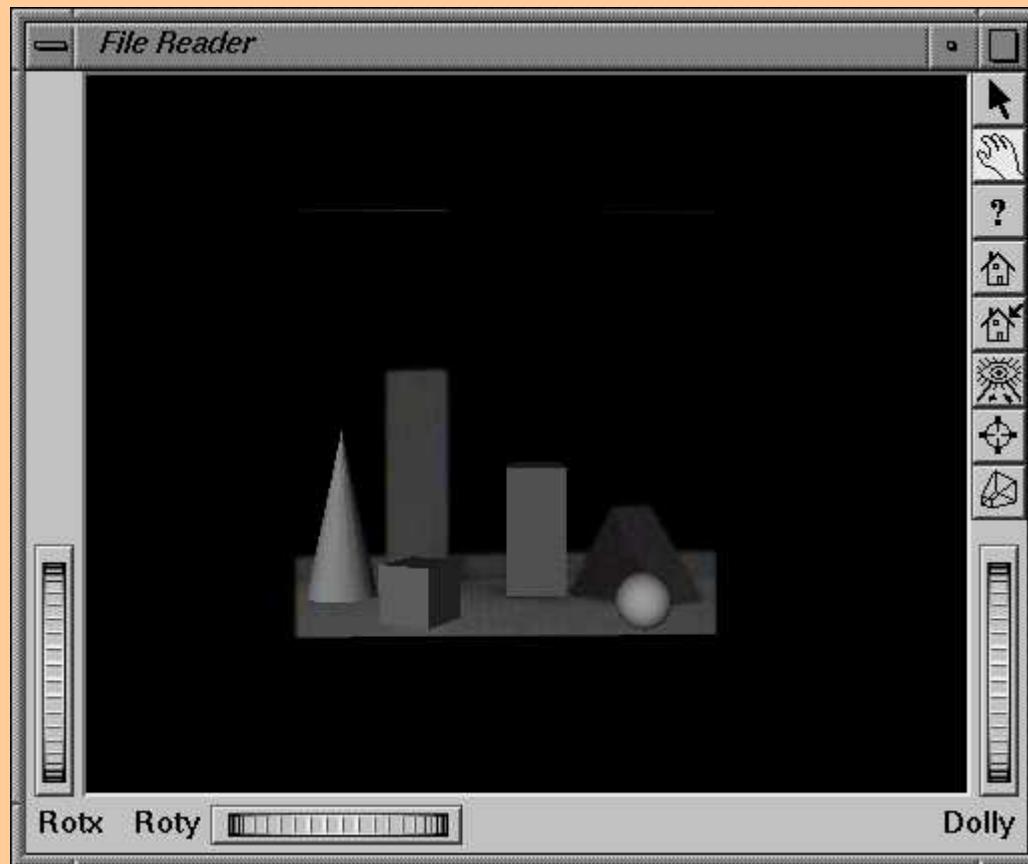
# Virtual camera movement



## Zoom

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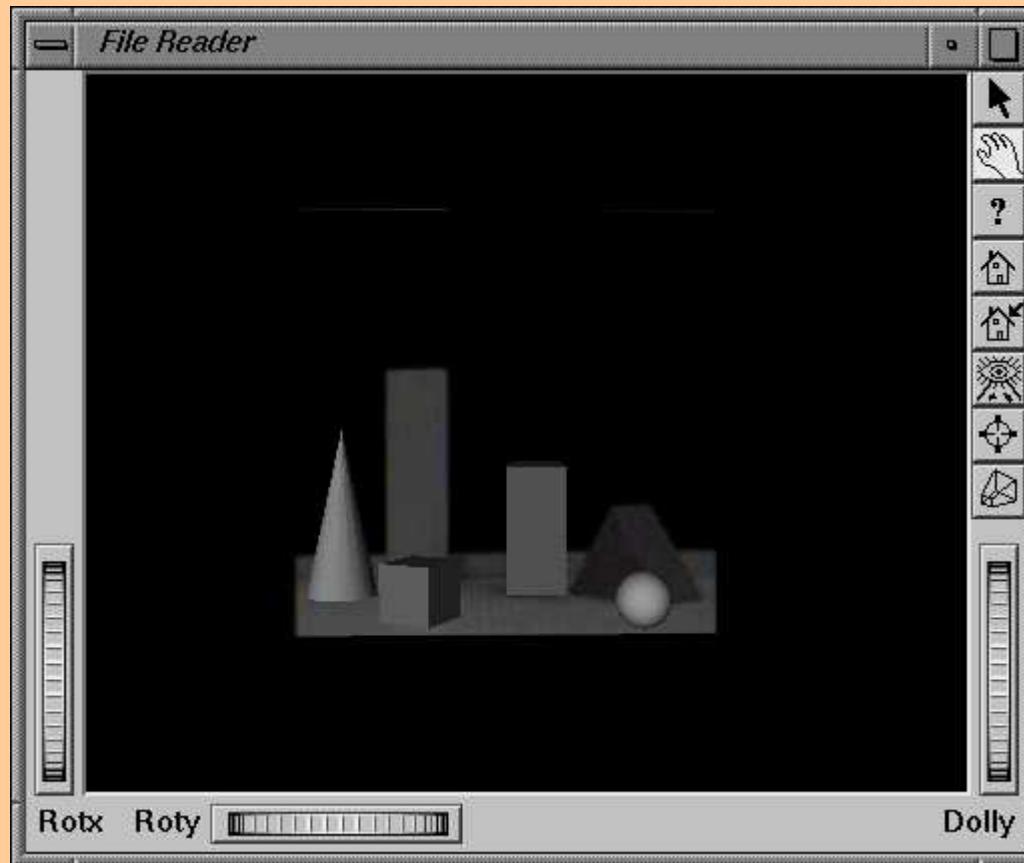
# Virtual camera movement



## Zoom

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# Virtual camera movement



## Tilt

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# CONCLUSIONS & FUTURE WORK

- Domestic production of virtual worlds
- Standard Tools (Open Inventor, VRML, ...)
- Simple calibration process with pinhole camera model
- Good degree of geometry coherence

# CONCLUSIONS & FUTURE WORK

- 3D Navigation: multiple cameras, virtual shooting
- Time Coherence in Animations (interactions between real and synthetic objects)
- Illumination Coherence (Lighting, shadows, ...)
- Study of more complex objects (deformable)
- More sofisticate mathematical tools (trilinear tensors, etc..)



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